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Operation



Properties and areas of application

The safe operation of machines, mechanical plant and their drives depends, to a large extent, on the forces and torques not exceeding the values on which the strength calculations for the particular clutch were based.

However, experience has shown that it is very difficult or impossible to calculate the exact loading for a particular application precisely in advance. In addition there is the risk of unwanted overloading occurring, for example, if stalling takes place. Ortlinghaus slipping and starting clutches have proved themselves to be excellent safety elements throughout the whole area of mechanical engineering for the elimination and dissipation of torque peaks. They provide protection against fracture for gears, gear wheels, shafts and other mechanical elements.

Recommendations for design and installation

When a clutch slips, mechanical energy is converted into heat, which requires to be dissipated either by means of radiation or, where clutches are installed in gearbox housings, by means of cooling oil.

Frictional connection is brought about by springs (1). The setting/adjustment device (2) allows the driving or slipping torque to be varied within certain limits in order to meet the requirements of the particular case of application.

The plates (**3**) of the clutches are supplied with the friction combinations steel/organic lining for dry running or steel/sintered lining for wet-running.

The permissible period during which slipping may take place depends on the amount of friction heat produced (slipping torque and the relative speed at which the plates slip past each other) and the capacity of the clutch to absorb heat.

When using these clutches for starting purposes, it must be taken into consideration that - despite the presence of the slipping clutch - the maximum output torque will be greater than the slipping torque set on the clutch.

Setting of the torque

The clutches are delivered as standard without set torque so that the clutch must be adjusted by the equipment maker. Under certain circumstances, the desired torque can also be set by Ortlinghaus. Instructions on setting are to be found in the respective technical product information.

Friction combination

The friction combination in the standard form of execution is steel/organic lining for dry-running. It is essential that the frictional surfaces are kept free of lubricants!

Steel/sintered lining for wet running on request.

Tolerances

For the tolerances for bores and keyways see section 1 "Technical information".

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Safety multi-plate slipping and starting clutches

Fig. 1 makes clear the benefits provided by a slipping clutch. If the amplitude of the torque peak to be expected without a slipping clutch M_O and also the ratio of this to the slipping torque M_R are known, the ratio of the maximum torque M_{max} to M_R for a given value of α can be read from the graph. If, for example, $\alpha = 0.02$ and if the torque peak (without slipping clutch) M_O is six times the slipping torque M_R , fitting the slipping clutch will reduce the torque peak to just 1.8 times the slipping torque M_R .







- M_{max} = Maximum torque at driven shaft
- M_{O} = Torque peak to be anticipated if no slipping clutch is used
- M_R = Slipping torque

$$\alpha \qquad = \frac{J_2}{J_1^{1+}J_2^{1+}}$$

- J₁ = Moment of inertia of driving machine and drive side of slipping clutch
- J₂ = Moment of inertia of driven side of slipping clutch
- J₃ = Moment of inertia of the driven side assumed to be inifinitely large

The figure shows that the driven side of the slipping clutch should have a low moment of inertia if the torque peaks to be expected are to be dissipated efficiently.

Slipping control

Multi-plate safety clutches are not recommended for high speed applications unless slip control is provided, since they can quickly overheat. The relative motion between the clutch halves that arises with overload slipping can be used to protect the unit by tripping out the prime mover. This can be done in various ways.

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1. Monitoring arrangement with cam and microswitch.





- K = Plug-type brush
- R = Slipring
- E = Microswitch on inner clutch member
- N = Cam on outer clutch member
- m = Earth
- S = Drive cut-out
- t = Time relay

This arrangement within the clutch has the disadvantage that small slipping movements can lead to undesired actuation of the microswitch and thus to the drive being cut out.

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2. Slipping control via solenoid switch signal

A safety arrangement which can be applied at an external point relative to the clutch is shown in Fig. 3. This uses signals from a solenoid switch to control a time relay. The arrangement permits slippage control from approx. 5 to 3,000 min⁻¹.





- a = Input
- b = Output
- c = Slipping clutch
- x = Clearance approx. 10 15 mm
- d = Permanent magnet, north pole
- e = Permanent magnet, south pole
- f = Solenoid switch
- t = Time relay

Permanent magnets - north and south poles - are attached to the shaft being monitored in such a way that they pass the solenoid switch with a clearance of 10 to 15 mm. The solenoid switch is actuated on each revolution thereby transmitting pulses to a time relay. The time relay remains energized as long as the period of time between two consecutive pulses remains less than the delay time preset on the relay. As this is about 1 s, the number of north and south poles must be chosen so that the time between consecutive pulses lies within this time as otherwise the relay will de-energize prematurely. If the time relay deenergizes, a hold line to the control contactor is interrupted and the drive is stopped.

In the standard version of the device, the drive will be cut out when the driven side comes to a complete or near complete standstill.

For applications where the driving speed changes, monitoring of the slippage by capturing the input and output side speeds of the clutch provides the greatest safety. Devices with electronic circuits have been developed for this purpose. With these, proximity-type pulse generators measure the speeds of the input and output sides of the clutch.

The two speeds are compared electronically. The pulses are triggered by markers fitted on each of the two sides. The markers may be in the form of cams, vanes, screwheads or holes, it is important that there are equal numbers of these on each side. The system is shown schematically in Fig. 4.





- a = Input
- b = Output
- c = Slipping clutch
- d = Marker e = Sensor
- f = Electronic module 1 for warning
- f = Electronic module 1 for warning f = Electronic module 2 for cut-out

If the clutch starts slipping so that a difference in the two speeds arises, electronic module 1 triggers first, causing an acoustic or optical warning signal to be given.

Electronic module 2 cuts out the drive if the period of time set on a time element is exceeded.

A time-controlled bridge is arranged to permit slipping while the machine is being started up.

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Safety multi-plate slipping and starting clutches



Application examples

Fig. 1: Slipping clutch, series **0600-474**, fitted between motor and gearbox on separate shafts. The bearings should be positioned as close as possible to the clutch.



Fig. 2: Slipping clutch, series **0600-474**, fitted in the feed drive of a boring and milling machine.



Fig. 3: Starting clutch, series **0700-070**, used in conjunction with a dog clutch.



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Multi-plate slipping clutches with hub housing





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Adequate clearance for a hexagonal socket key must be provided on the clutch face to permit adjustment (see page 3b.06.00, Fig. 1)

| Series | | | 0600- | 424-Size-0.0 | 09. | 0600-474-Size-0.0091 | | | | | |
|------------------------------------|----------------------------------|--|----------------|------------------|-------------------|----------------------|-------------------|--|---------------------|--|--|
| Size-version | | | 07-0.0-092 | 11-0.0-091 | 15-0.0-091 | 223 | 3 31 | 3 39 | 3 47 | | |
| Mstat ¹⁾ | -000-09. -010-09. -020-09. | approx. Nm approx. Nm approx. Nm | 30 20 10 | 60 40 20 | 100 70 35 | 200 140 70 | 500 350 180 | 1000 700 350 | 1600 1100 550 | | |
| Mstat min | -020-09. | approx. Nm | 9 | 10 | 28 | 0 | 75 | 130 | 180 | | |
| J | internal external | kgcm ² kgcm ² | 33 | 5 25 | 8 50 | 20 200 | 50 250 | 150 500 | 350 1350 | | |
| Weight | | approx. kg | 2,4 | 4 | 5,5 | 9,8 | 10,5 | 18,5 | 31 | | |
| ØA | prebored | | 10 | 10 | 15 | 18 | 18 | 28 | 30 | | |
| | A _{max} Keyway I | H7 DIN 6885 | 20 6x2,8 | 30 8x3,3 | 40 12x3,3 | 48 14x2,1 | 60 18x2,3 | 70 20x2,7 | 80 22x5,4 | | |
| | A Keyway I | H7 DIN 6885 | 18 6x2,8 | 28 8x3,3 | 38 10x3,3 | 45 14x3,8 | 45 14x3,8 | 50 14x3,8 | 55 16x4,3 | | |
| Recommended bores ²⁾ | A Keyway I | H7 DIN 6885 | 16 5x2,3 | 25 8x3,3 | 35 10x3,3 | 40 12x3,3 | 40 12x3,3 | 45 14x3,8 | 50 14x3,8 | | |
| | A Keyway I | H7 DIN 6885 | 15 5x2,3 | 22 6x2,8 | 30 8x3,3 | 35 10x3,3 | 35 10x3,3 | | 45 14x3,8 | | |
| | A Keyway I | H7 DIN 6885 | 12 4x1,8 | 20 6x2,8 | 25 8x3,3 | 30 8x3,3 | | | | | |
| Diameters | B D | | 70 | 90 | 100 | 125 | 80 150 | 120 170 | 130 210 | | |
| | L M N | | 90 0 5 | $\frac{105}{-1}$ | 110 - 1 | 125 | 130 88 2 | $ \begin{array}{r} 170 \\ 108 \\ 2 \end{array} $ | 195 128 2 | | |
| Length dimensions | O P R | | 35 89,5 | 45 104 | 45 109 | 55 123,5 | 40 50 | 60 70 | 65 80 - | | |
| | V | | 55 | 60 | 65 | Ź0 | 80 | 100 | 115 | | |

¹⁾ Mstat decreases to approx. ²/₃ of the stated values with wet-running. The clutches are delivered as standard without set torque so that the clutch must be adjusted by the equipment maker. Under certain circumstances, the desired torque can also be set by Ortlinghaus. Instructions on setting are to be found in the respective technical product information.

²⁾ Bore diameters in bold print are available ex stock.

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Multi-plate slipping clutches with flange or shoulder housing



with flange housing, closed version

Available for delivery in open version on request, without case cover and closure plug but with peripheral holes: series 0600-071

Series 0600-070



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Series 0600-072 with shoulder housing, closed version Available for delivery in open version on request, without case cover and closure plug but with peripheral holes: series 0600-073

| Series | | | | 0600-070- | Size-0.0091 Size-0.0091 | L 1 | 0600 | -070-Size-0 -072-Size-0 | .0095 |
|----------------------------------|--|---|---|--|---|---|---|---|--|
| Size | | | 47 | 55 | 63 | 69 | 75 | 78 | 84 |
| Mstat ¹⁾ | -000-09. -010-09. -020-09. | approx. Nm approx. Nm approx. Nm | 1600 1100 550 | 2800 2000 1000 | 6000 4000 2000 | 10000 7000 3500 | 18000 12000 6000 | $23000 \\ 16000 \\ 8000$ | 30000 20000 10000 |
| Mstat min | -020-09. | approx. Nm | 90 | 700 | 1200 | 500 | 0 | 0 | 0 |
| J | 0600-070 0}}600-072 | internal kgm ² external kgm ² external kgm ² | 0,055 0,08 0,075 | 0,158 0,21 0,195 | 0,34 0,458 0,425 | 0,75 1,05 0,975 | 1,975 2,075 1,925 | 3,5 3,425 3,2 | 12,75 11,5 10,625 |
| Weight | | approx. kg | 22 | 39 | 61 | 99 | 165 | 224 | 454 |
| ØA | prebored | 1 | 30 | 32 | 48 | 48 | 60 | 60 | 100 |
| | A _{max} Keyway | H7 DIN 6885 | 80 22x5,4 | 80 22x5,4 | 110 28x6,4 | 130 32x7,4 | 170 40x9,4 | 190 45x10,4 | 220 50x11,4 |
| Recomment bores ²⁾ | ded A Keyway | H7 DIN 6885 | 60 18x4,4 | | | | | | |
| | A Keyway | H7 DIN 6885 | 55 16x4,3 | | | | | | |
| Diameters | B B1 C C1 D E H7 F G G1 H Number | of bores | 250 225 230 205 210 195 | 310 285 285 260 260 245 90 13 M12 19,5 6 | 370 335 340 310 315 295 125 15 M12 23,5 6 | 430 395 400 365 370 345 142 17 M14 25,5 6 | $500 \\ 460 \\ 470 \\ 430 \\ 435 \\ 410 \\ 200 \\ 17 \\ M14 \\ 25,5 \\ 6$ | 550 515 520 485 490 465 220 17 M16 25,5 6 | 750 700 655 650 620 300 26 M24 - |
| Length dimensions | O O1 P R S T U V | | $ \begin{array}{c} 12\\ 20\\ 5\\ 6\\ 10\\ -\\ 120 \end{array} $ | 15 25 10 7,5 15 2 12 128 | 15 25 10 7,5 15 2 15 135 | $20 \\ 35 \\ 10 \\ 10 \\ 15 \\ 5 \\ 20 \\ 155$ | $ \begin{array}{r} 20 \\ 35 \\ 10 \\ 10 \\ 15 \\ 5 \\ 18 \\ 185 \end{array} $ | $20 \\ 45 \\ 10 \\ 10 \\ 15 \\ 5 \\ 20 \\ 195$ | 25 45 15 20 5 20 205 |

 $^{1)}$ M_{stat} decreases to approx. 2 /3 of the stated values with wet- running. The clutches are delivered as standard without set torque so that the clutch must be adjusted by the equipment maker. Under certain circumstances, the desired torque can also be set by Ortlinghaus. Instructions on setting are to be found in the respective technical product information.

²⁾ Bore diameters in bold print are available ex stock.

Sliding plate clutches in special sizes of approx. 300,000 Nm are possible! Adequate clearance for a hexagonal socket key must be provided on the clutch face to permit adjustment (see page 3b.06.00, Fig. 1)

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Multi-plate starting clutches



Nut = Keyway



| Series | | | 070 | 0700-000-Size-0.109. | | | | 0700-070-Size-0.1091 | | | |
|------------------------------------|----------------------------------|--|--|--|--------------------------------------|----------------------------|----------------------------|------------------------------|--|----------------------------|--|
| Figure Size-version | | | 07-0.1-092 | 1 11-0.1-091 | 15-0.1-091 | 2 23 | 25 | 3 31 | 3 39 | 47 | |
| Mstat ¹⁾ | -001-09. -011-09. -021-09. | approx. Ni approx. Ni approx. Ni | n 30 n 20 n 10 | 60 40 20 | 100 70 35 | 160 100 50 | 250 180 90 | 500 350 180 | 1000 700 350 | $1600 \\ 1100 \\ 550$ | |
| Mstat min | -021-09. | approx. Ni | n 9 | 11 | 30 | 28 | 0 | 130 | 130 | 150 | |
| J | internal external | kgcm kgcm | $\begin{bmatrix} 2\\2\\3\end{bmatrix}$ | 5 25 | $\begin{array}{c} 8\\ 40\end{array}$ | 20 100 | 23 150 | 50 350 | $\begin{array}{c} 150\\ 450 \end{array}$ | 350 1175 | |
| Weight | | approx. k | g 1,5 | 2,8 | 4 | 6 | 6,5 | 12 | 16 | 30 | |
| ØA | prebored | | 10 | 10 | 15 | 18 | 18 | 18 | 22 | 30 | |
| | A _{max} Keyway I | H DIN 688 | 7 20 5 6x1,6 | 30 8x2 | 38 10x3,3 | 48 14x2,1 | 48 14x2,1 | 55 16x2,4 | 65 18x2,3 | 80 22x5,4 | |
| | A Keyway I | H DIN 688 | 7 18 5 6x2,8 | 28 8x3,3 | 35 10x3,3 | 45 14x3,8 | 45 14x3,8 | 50 14x3,8 | 50 14x3,8 | | |
| Recommended bores ²⁾ | A Keyway I | H DIN 688 | 7 18 5 6x1,6 | 25 8x3,3 | 32 10x3,3 | 40 12x3,3 | 40 12x3,3 | 45 14x3,8 | 45 14x3,8 | | |
| | A Keyway I | H DIN 688 | 7 16 5 5x2,3 | 24 8x3,3 | 30 8x3,3 | 35 10x3,3 | 35 10x3,3 | | | | |
| | A Keyway I | H DIN 688 | 7 14 5 5x2,3 | 20 6x2,8 | 28 8x3,3 | 30 8x3,3 | 30 8x3,3 | | | | |
| Keyway II | | | | 8 wide, 4 dee | р | | | 12 breit, 4 | ,5 tief | | |
| Diameters | D n6 E | | 70 | 90 38 | $100\\48$ | 125 | 135 | 150 | 170 | 210 | |
| Length dimensions | L M N O P V | | 60 30 0,5 59,5 - | 68 45 1 67 4,5 63 | 74 45 1 73 4 70 | 80 50 1,5 77 - | 80 50 1,5 77 - | 105 50 0,5 104 – | 125 50 0,5 124 – | 150 70 1 148 - | |
| Series | | | Vers | Version without keyway II; dimensions as above plus dimension D _{max} | | | | | nax | | |
| J | inte exte | rnal kgcm rnal kgcm | | 5 125 | 8 200 | 20 350 | 23 450 | 50 1225 | 150 1875 | 350 4500 | |
| Weight | app | rox. k | g 3,4 | 6,4 | 8,3 | 10,7 | 11,5 | 23,5 | 30 | 52 | |
| Ø D max | | | 100 | 130 | 140 | 160 | 170 | 200 | 220 | 270 | |

¹⁾ Mstat decreases to approx. ²/₃ of the stated values with wet-running. The clutches are delivered as standard without set torque so that the clutch must be adjusted by the equipment maker. Under certain circumstances, the desired torque can also be set

by Ortlinghaus. Instructions on setting are to be found in the respective technical product information.

²⁾ Bore diameters in bold print are available ex stock.

Adequate clearance for a hexagonal socket key must be provided on the clutch face to permit adjustment (see page 3b.06.00, Fig. 1)

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